

Coordinate Changes for Integrals

IDEA: In Calculus I you used coordinate changes to solve

$$\textcircled{1} \quad \int_{x=0}^5 xe^{x^2} dx \quad \begin{cases} u = x^2 \leftarrow \text{coordinate change,} \\ du = 2x dx \text{ Parametrizes } \mathbb{R} \end{cases}$$

↑
necessary differential composition

(a) Polar coordinate change

$$\iint_R e^{x^2+y^2} dA \rightarrow \iint_R r e^{r^2} dA \quad \begin{cases} x = r \cos \theta \\ y = r \sin \theta \end{cases}$$

We want a more general way to compute these coordinate changes for integrals (more differential equations easier)

Answer: Jacobians!

Defn: Jacobian of a coordinate change

$$\begin{cases} x_1 = x_1(u_1, u_2, \dots, u_n) \\ x_2 = x_2(u_1, u_2, \dots, u_n) \\ \vdots \\ x_n = x_n(u_1, u_2, \dots, u_n) \end{cases}$$

$$\frac{d(x_1, x_2, \dots, x_n)}{d(u_1, u_2, \dots, u_n)} = \begin{bmatrix} \frac{\partial x_1}{\partial u_1} & \frac{\partial x_1}{\partial u_2} & \dots & \frac{\partial x_1}{\partial u_n} \\ \frac{\partial x_2}{\partial u_1} & \frac{\partial x_2}{\partial u_2} & \dots & \frac{\partial x_2}{\partial u_n} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial x_n}{\partial u_1} & \frac{\partial x_n}{\partial u_2} & \dots & \frac{\partial x_n}{\partial u_n} \end{bmatrix}$$

Example: Jacobian of polar coordinate change is

$$\frac{\partial(x_1, x_2)}{\partial(r, \theta)} = \det \begin{bmatrix} \frac{\partial x}{\partial r} & \frac{\partial x}{\partial \theta} \\ \frac{\partial y}{\partial r} & \frac{\partial y}{\partial \theta} \end{bmatrix}$$

$$= \cos \theta (r \cos \theta) - (\sin \theta (-r \sin \theta)) = r(\cos^2 \theta + \sin^2 \theta) = r$$

NB: if we reverse order of (r, θ) , we get

$$\frac{d(x,y)}{d(\theta,r)} = \det \begin{bmatrix} \frac{\partial x}{\partial \theta} & \frac{\partial x}{\partial r} \\ \frac{\partial y}{\partial \theta} & \frac{\partial y}{\partial r} \end{bmatrix} = \det \begin{bmatrix} -r \sin \theta & \cos \theta \\ r \cos \theta & \sin \theta \end{bmatrix}$$

$$= -r \sin \theta \cos \theta - r \cos \theta \cos \theta$$

$$= -r (\sin^2 \theta + \cos^2 \theta) = -r$$

Def // The (unsigned) Jacobian of a transformation is simply

$$\left| \frac{\partial(x_1, x_2, \dots, x_n)}{\partial(u_1, u_2, \dots, u_n)} \right|$$

Prop: Let $f(x_1, x_2, \dots, x_n)$ be a function continuous on \mathbb{R}^n and

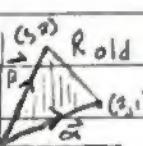
$$\begin{cases} x_1 = x_1(u_1, \dots, u_n) \\ \vdots \\ x_n = x_n(u_1, \dots, u_n) \end{cases}$$

Change by diff. fractions

$$\int_{\text{old}} f(x_1, \dots, x_n) d\text{vol} = \int_{\text{new}} f(x_1(u_1, \dots, u_n), \dots, x_n(u_1, \dots, u_n)) \cdot \left| \frac{\partial(x_1, \dots, x_n)}{\partial(u_1, \dots, u_n)} \right| d\text{vol}_{\text{new}}$$

Example: compute $\iint_R (x-2y) dA$ for the triangle w vertices $(0,0), (1,2), (2,1)$

$$(x,y) =$$

(u_1, u_2)  Sol 1: using cartesian, split region and compute
(do this on your own)

Sol 2: using a simple transformation

$$(u, v) = (1, 0) \rightarrow (x, y) = (2, 1)$$

$$(u, v) = (0, 1) \rightarrow (x, y) = (1, 2)$$

$$\begin{cases} x = 2u + v \\ y = u + 2v \end{cases}$$

check that first triangle maps to second

Moreover, $R_{\text{new}} = \{(u, v) : 0 \leq u \leq 1, 0 \leq v \leq 1-u\}$

$$\begin{aligned} \frac{d(x, y)}{d(u, v)} &= \det \begin{bmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{bmatrix} = 4 - 1 = 3 \\ \therefore \iint_R (x-2y) dA &= \iint_{R_{\text{new}}} (2u+v) - 2(u+v) \cdot 3 dA_{\text{new}} \\ &= 3 \iint_{u \geq 0, v \geq 0} -3v du dv \\ &= -9 \int_0^1 \left(\frac{1}{2} v^2 \right)_{v=0}^{1-u} du = -9/2 \int_{u=0}^1 (1-u)^2 \\ &= 9/2 \left(1/3 \left[(1-u)^3 \right] \Big|_{u=0}^1 \right) = 3/2 (-1) = \boxed{-3/2} \end{aligned}$$

Generalizing Polar Coordinates To 3-Space

I) Cylindrical Coordinates

IDEA: Parameterize one plane w/ polar coordinates,
leave orthogonal axis alone...

In particular, this coordinate change is

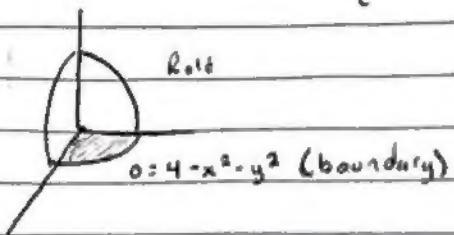
$$\begin{cases} x = r \cos \theta \\ y = r \sin \theta \\ z = z \end{cases}$$

Differential: $\frac{d(x, y, z)}{d(r, \theta, z)} = \begin{bmatrix} \cos \theta & -r \sin \theta & 0 \\ \sin \theta & r \cos \theta & 0 \\ 0 & 0 & 1 \end{bmatrix}$

$$\begin{aligned} \cos \theta (r \cos \theta) + r \sin \theta (\sin \theta) + 0(r \cos^2 \theta + r \sin^2 \theta) \\ = r (\cos^2 \theta + \sin^2 \theta) \\ = r \end{aligned}$$

Takeaway: $dA_{\text{Cartesian}} = r dA_{\text{cylindrical}}$ for all cylindrical transformations

Example: Compute $\iiint_E (x+y+z) dv$, E in first octant, parabola
 $4-x^2-y^2 \geq z$



Sol: parametrize cylindrical coordinates

$$\begin{cases} x = r \cos \theta \\ y = r \sin \theta \\ z = z \end{cases} \quad R_{\text{new}} = \begin{cases} 0 \leq r \leq 2 \\ 0 \leq \theta \leq \pi/2 \\ 0 \leq z \leq 4 - r^2 \end{cases}$$

$$\therefore \iiint_E (x+y+z) dv = \iiint_{E_{\text{cyl}}} (r \cos \theta + r \sin \theta + z) r dr d\theta dz$$

$$= \int_0^2 \int_0^{4-r^2} \int_0^{\pi/2} (r \cos \theta + r \sin \theta + z) r dr d\theta dz$$

$$= \int_{r=0}^2 \int_{z=0}^{4-r^2} \left[r \sin \theta - r \cos \theta + \frac{1}{2} z^2 \right]_{\theta=0}^{\pi/2} dr dz$$

$$= \int_{r=0}^2 \int_{z=0}^{4-r^2} 2r^2 + \frac{\pi}{2} z^2 dr dz$$

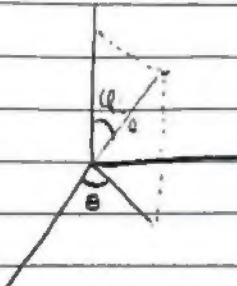
$$= \int_{r=0}^2 \int_{z=0}^{4-r^2} 2r^2 z + \frac{\pi}{4} r z^2 \Big|_0^{4-r^2} dr dz$$

$$= \int_0^2 (8r^2 - 2r^4 + \frac{\pi}{4}(16r - 8r^3 + r^5)) dr$$

$$= \left[\frac{8}{3}r^3 - \frac{2}{5}r^5 + \frac{\pi}{4} \left(16r - 8r^3 + \frac{1}{2}r^5 \right) \right]_{r=0}^2$$

$$= 64/3 - 64/5 + \pi^8/3$$

II Spherical coordinates: Every point in \mathbb{R}^3 lies on a sphere

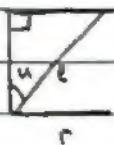


we parametrize via

$r = \text{distance from } (x, y, z) \text{ to origin}$

$\theta = \text{angle from } z \text{ axis to point } (x, y, 0)$

$\phi = \text{angle from } y \text{ axis to point } (x, y, z)$



$$\left\{ \begin{array}{l} x = r \cos \theta \rightarrow r \sin(\theta) \cos \theta \\ y = r \sin \theta \rightarrow r \sin(\theta) \sin \theta \\ z = r \cos(\phi) \end{array} \right.$$